Computational Fluid Dynamics Modeling of High Level Waste Plug Formation – 14359

Romani Patel *, Georgio Tachiev *, Dwayne McDaniel *, Deanna Moya * * Florida International University

ABSTRACT

At Hanford, an extensive network of pipelines traversing several miles are used to transfer the high level radioactive nuclear waste from tanks to the treatment facilities. During transfer operations, however, the potential for solids to settle along the pipeline frequently exists resulting in partial or sometime full plugging of the pipelines. In this study we investigate the phenomena of plug formation in the pipelines due to solids depositing during the waste transfer process. A Computational Fluid Dynamics (CFD) model has been developed by Florida International University (FIU) to predict the settling of solids in a pipeline using the macroscopic two phase mixture model, turbulent interface implemented in COMSOL Multiphysics 4.3b. The settling of solids is simulated as a function of flow velocity, particle size, solids density and volume fraction of solids. The results are validated by experimental results and critical velocity correlations.

INTRODUCTION

A vast amount of radioactive waste has been stored at Hanford spanning several decades. A majority of this waste is stored in tanks and is transferred in the slurry form between tanks and from tanks to processing facilities. A waste transfer system consisting of an extensive network of pipelines is used to facilitate the transfer operations. The main goal of the waste transfer system is to transfer the nuclear waste without plugging the transfer pipelines. Currently, two tools have been used to support this objective and include the Environmental Simulation Program (ESP) and empirical based critical velocity correlations. First, ESP is used to estimate the initial waste compositions and solids volume fraction. Then critical velocity correlations are used to estimate the minimum velocity to prevent settling of solids during waste transfers.

Despite such efforts, several lines have plugged during the waste transfer process at Hanford. The plugging has been attributed to two main factors: chemical instability and settling of solids. Chemical instability during waste transfers results is a phase change (from liquid to solid) initiated due to drops in temperature, changes in local concentration or mixing and pumping of wastes that are not in equilibrium. The solid phase precipitates or crystallizes depending on the solubility characteristics of the dissolved multiple species of the waste, their chemical interaction, and temperature. The solids may precipitate out of the solution and accumulate along the pipe walls. The pipe walls then serve as a nucleation site where the solids nucleate and grow rapidly and eventually form an interlocking needle-like crystal network. The needle-like crystal network impedes the flow within the pipe and commences the formation of the plug [1]. The presence of precipitates and/or agglomerates increases the solids concentration and increases viscosity of the slurry. The flow transitions from turbulent to laminar as a result of such changes during transit and the undissolved solids may settle when the flow velocity is not sufficient to keep them suspended. A moving bed of particles then begins to accumulate during slurry transport operation. Settling solids in a moving bed of particles form a stationary bed that eventually fills the pipe and blocks flow.

The blocked pipelines pose several problems at Hanford. The plugged pipelines are considered hazardous, hard and expensive to repair and cause significant time delays in the clean-up

process. Consequently, most plugged transfer pipelines are abandoned. The phenomenon of settling of solids has been the subject of numerous theoretical and experimental studies [2, 3]; however, these require extensive experimental set-ups, procuring varied slurries, and carrying out lengthy experimental trials. The theoretical studies rely heavily on empirical formulae which do not take full account of the settling physics. The settling of solids depends on various physical characteristics of the suspended solids such as particle size, density, flow velocity, volume fraction of solids, etc. A need exists for an inexpensive computational tool that can investigate the influence of various parameters that affect the settling of solids and better aid in understanding the settling dynamics at a click of a button.

A two dimensional (2D) computational analysis has been carried out at FIU simulating settling of solids in a horizontal pipeline as a function of flow velocity, particle size and volume percent solids using the CFD software COMSOL Multiphysics 4.3b. The numerical results are validated with empirical correlations and experimental results. The outline of the paper is given as follows: First, the governing equations for the mixture model simulations are introduced. Second, simulations modeling settling of solids are presented. Finally, conclusions are drawn and discussions for future work are presented.

NUMERICAL IMPLEMENTATION

The slurry flow in a horizontal pipeline was computed using the mixture model that is part of the Chemical Engineering module of COMSOL Multiphysics 4.3b. The mixture model is a macroscopic two phase model that is able to compute the flow for a mixture of a solid and liquid. It tracks the average phase concentration, or volume fraction and solves for one velocity field for each phase. The two phases consisted of one dispersed phase (solid particles) and one continuous phase (liquid). The model combined the k-epsilon turbulence model for the main flow with equations for the transport of the dispersed phase and the relative velocity of both phases. Some of the assumptions made while using the mixture model are that the density of each phase was constant; that the pressure field was same and the velocity between the two phases could be ascertained from a balance of pressure, gravity, and viscous drag [4].

Governing Equations

The mixture model treats both the continuous as well as the dispersed phase as a single mixture with a slip velocity between them. The momentum equation for the mixture is given by

$$\rho u_t + \rho (u \cdot \nabla) u = -\nabla p - \nabla \cdot \tau_{Gm} + \rho g + F$$

$$-\nabla \cdot \left[\rho c_d (1-c_d) \left(u_{slip} - \frac{D_{md}}{(1-c_d)\phi_d} \nabla \phi_d \right) \left(u_{slip} - \frac{D_{md}}{(1-c_d)\phi_d} \nabla \phi_d \right) \right]$$
(1)

where, *u* denotes mixture velocity (m/s), ρ is the mixture density (kg/m³), *p* is the pressure (Pa), c_d is the mass fraction of the dispersed phase (kg/kg), u_{slip} is the relative velocity between the two phases (m/s), τ_{Gm} is the sum of viscous and turbulent stress (kg/(m·s²)), *g* is the gravity vector (m/s²), and *F* is the additional volume forces (N/m³).

The velocity *u* used here is the mixture velocity which is defined as

$$u = \frac{\phi_c \rho_c \mu_c + \phi_d \rho_d \mu_d}{\rho}$$
(2)

Here, *c* and *d* denote the volume fractions of the continuous phase and the dispersed phase (m^3/m^3) , respectively, u_c is the continuous phase velocity (m/s), u_d is the dispersed phase velocity (m/s), ρ_c is the continuous phase density (kg/m³), ρ_d is the dispersed phase density (kg/m³), and ρ is the mixture density (kg/m³).

The relationship between the velocities of the two phases is defined by

$$u_d - u_c = u_{cd} = u_{slip} - \frac{D_{md}}{(1 - c_d)\phi_d} \nabla \phi_d$$
(3)

Here, u_{slip} (m/s) denotes the slip velocity between the two phases, and D_{md} is a turbulent dispersion coefficient (m²/s) accounting for extra diffusion due to turbulent eddies.

The Schiller-Naumann model was used to compute the slip velocity which uses the following relation,

$$\frac{3}{4}\frac{C_d}{d_d}\rho_c \left|\mu_{slip}\right|\mu_{slip} = \frac{(\rho - \rho_d)}{\rho}\nabla p \tag{4}$$

where, C_d is the dimensionless particle drag coefficient and is defined as

$$C_d = \frac{24}{Re} (1 + 0.15Re^{0.687}), Re \le 1000$$
(5)

and

$$C_d = 0.44, Re \ge 1000$$
 (6)

The mixture density ρ is given by

$$\rho = \varphi_c \rho_c + \varphi_d d \tag{7}$$

where ρ_c and ρ_d (kg/m³) are the densities of each of the two phases.

The mass fraction of the dispersed phase c_d is given by

$$c_d = \frac{\phi_d \rho_d}{\rho} \tag{8}$$

The sum of viscous and turbulent stress is

$$\tau_{Gm} = (\mu + \mu_T) [\nabla u + \nabla u^T]$$
(9)

where, μ (Pa·s) is the mixture viscosity and μ_T (Pa·s) the turbulent viscosity.

The transport equation for ϕ_d , the dispersed phase volume fraction, is

$$\frac{\partial}{\partial t}(\varphi_d \rho_d) + \nabla \cdot (\varphi_d \rho_d u_d) = -m_{dc}$$
(10)

where, m_{dc} (kg/(m³·s)) is the mass transfer rate from dispersed to continuous phase and u_d (m/s) is the dispersed phase velocity according to Eq. (3).

Assuming constant density for the dispersed phase Eq. (7) is rewritten as,

$$\frac{\partial}{\partial t}(\phi_d) + \nabla \cdot (\phi_d u_d) = -\frac{m_{dc}}{\rho_d}$$
(11)

The continuous phase volume fraction, ϕ_c , is

$$\varphi_c = 1 - \varphi_d \tag{12}$$

and the continuity equation for the mixture is given as

$$\rho_t + \nabla \cdot (\rho u) = 0 \tag{13}$$

The Mixture Model interfaces assumes that the densities of each phase, ρ_c and ρ_d are constant, and therefore uses the following alternative form of the continuity equation of the mixture,

$$(\rho_c - \rho_d) \left[\nabla \cdot (1 - c_d) \boldsymbol{u}_{slip} - D_{md} \nabla \phi_d \right] + \frac{m_{dc}}{\rho_d} + \rho_c (\nabla \cdot \boldsymbol{u}) = 0$$
(14)

The flow turbulence is modeled using the k- ϵ turbulence model which solves two extra transport equations for the turbulent kinetic energy, k and the dissipation rate of turbulent kinetic energy, ϵ as described below. The turbulent viscosity is given by

$$\eta_T = \rho C_\mu \frac{k^2}{\varepsilon} \tag{15}$$

where, C_{μ} is a model constant and is equal to 0.09.

The transport equation for the turbulent kinetic energy k is

$$\rho \frac{\partial k}{\partial t} + \rho \mu \cdot \nabla k = \nabla \cdot \left(\left(\mu + \frac{\mu_T}{\sigma_k} \right) \cdot \nabla k \right) + P_k - \rho \varepsilon$$
(16)

where the production term is

$$P_k = \mu_T (\nabla \mu: (\nabla \mu + (\nabla \mu)^T) - \frac{2}{3} (\nabla \cdot \mu)^2) - \frac{2}{3} \rho k \nabla \cdot \mu$$
(17)

The turbulent kinetic energy, ε , is determined by

$$\rho \frac{\partial \varepsilon}{\partial t} + \rho \mu \cdot \nabla \varepsilon = \nabla \cdot \left(\left(\mu + \frac{\mu_T}{\sigma_{\varepsilon}} \right) \cdot \nabla \varepsilon \right) + C_{\varepsilon 1} \frac{\varepsilon}{k} P_k - C_{\varepsilon 2} \rho \frac{\varepsilon^2}{k}$$
(18)

where, C_{ε_1} , C_{ε_2} , σ_k , and σ_{ε} , are model constant and the values used were 1.44,1.92,1 and 1.3, respectively.

Model Geometry and Boundary Conditions

The model geometry for the simulations consisted of a two dimensional (2D) horizontal pipe with a diameter of 0.078 m and a length of 5.2 m. The slurry was modeled as a Newtonian suspension

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consisting of solids particles dispersed in liquid. The mixture entered through the inlet at velocities characterizing fully developed turbulent flow regimes. The turbulence intensity and length scale were set to 5% and $0.07*r_{in}$ where $r_{in} = 0.039$ is the radius of the inlet. The solids were modeled as spherical solid particles of equal size with the particle size ranging from 14.4-220 µm. The solid volume fraction ranged from 2.9-9.8%. The solid densities ranged from 1000-8000 kg/m³ and the liquid densities ranged from 999-1647 kg/m³. The outlet was set to zero pressure, no viscous stress and the dispersed phase flow exited the pipe at mixture velocity. A slip boundary condition was selected at the top wall assuming that the fluid at the wall was moving whereas the bottom wall had a no-slip boundary condition. A gravity node was added to account for the gravity force in the negative y-direction over the entire domain. Initially, the velocity as well as the solids phase volume fraction was zero in the entire model domain. The mesh used to partition the model domain into sub-domains consisted of triangular elements. A finer mesh size was used at the walls compared to the rest of the model domain to resolve variations in the flow speed at the wall boundaries and help in achieving the convergence of the model as shown in Fig. 1.





Numerical Simulations

The mixture model to simulate settling of solids is solved via a transient simulation. The behavior of settling was investigated as a function of flow velocity, particle size, solids density and solids volume fraction. TABLE I below lists the material properties used for the numerical simulations.

	Model Verification Study				
Test Configuration	1	2	3	4	5
Particle diameter (µm)	14.4	37.7	129.5	182.3	203.9
Solids Density (kg/m³)	2500	7950	3770	2500	7950
Solids volume fraction (%)	9.8	9.3	8.7	7.4	3.0
Liquid density (kg/m ³)	1146	1647	1151	999	1026
Liquid viscosity (cP)	10.2	9.3	4.5	1.5	1.6

TABLE I. NUMERICAL SIMULATIONS MATRIX

The material properties were obtained from the experimental tests done by Pacific Northwest National Laboratory (PNNL) to determine the critical velocity for Newtonian slurries. The critical velocity obtained by the numerical simulations was compared with the experimental results of PNNL and with the empirical based critical velocity correlations. The numerical results were a good match with the experimental results and demonstrated the use of COMSOL Multiphysics 4.3b to accurately simulate the settling physics as shown in Fig. 2.



Fig. 2. Comparison of numerical results to experimental and empirical results.

The main problem with using the critical velocity correlations to determine the velocity of the transfer operations is that the equation is based on single component density particles forming narrowband PSD. The use of the equation for multi-component density particles, broadband PSDs, and/or median particle sizes less than 100 µm (typical Hanford waste) requires extrapolation beyond the database used in the development of equation. Hence, the equation should be used with caution when applied for any of these conditions. Moreover, the PSD is assumed to be static while deriving these correlations. But in actual waste transfers, the PSD is dynamic due to precipitation, particle agglomeration, and particle-surface interactions. The correlations do not provide information about the solids volume fraction, temperature, local velocity profile, PSD, etc along the length of the pipe nor any information on how these quantities change with time. The correlation is applicable for calculating the critical velocity of Newtonian fluids in straight, horizontal piping. When applied to non-Newtonian fluids in horizontal piping, these correlations under-predict the critical velocities [3]. Moreover, the transfer lines consists of vertical segments, pipe bends, Tee's, reducers, jumpers, connector and various other pipe components which can affect the critical velocity and plug formation process and the empirical formulae does not consider such complex piping components.

a. Influence of Particle Size

The effect of particle size on the settling dynamics was investigated using 45 μ m and 200 μ m size solids particles dispersed in water. The solids density was kept constant at 3147 kg/m³ and the liquid density used was 1000 kg/m³. The solids volume fraction was 2.9%. The simulations were carried out with entrance velocities ranging from 0.5 m/s to 2 m/s. The 45 μ m and 200 μ m particle

concentrations at different velocities are shown in Fig. 3 and Fig. 4. The color legend represents the different solids concentration in the pipe.



Fig. 3. A 45 μm particle concentration along the pipe as a function of flow velocity ranging from 0.5 to 2 m/s



Fig. 4. A 200 μm particle concentration along the pipe as a function of flow velocity ranging from 0.5 to 2 m/s

The concentrations figures show that the 220 μ m larger and heavier particles tend to settle fast on the bottom of the pipe, especially at low flow velocities. The simulations showed that flow velocities of lower than 1.0 m/s will create a stationary bed flow that eventually causes a plug to form. For velocities of greater than 1.0 m/s, the fluid establishes a moving bed regime where the particles move along the bottom of the transfer pipe.

b. Influence of Solids Density

The effect of solids density on the settling dynamics was investigated by running simulations for the 45 μ m particle size and 2.9% solids volume fraction at solids densities of 3147 kg/m³ and 6300 kg/m³. The entrance velocities used were 0.5 m/s, 1 m/s and 2 m/s. The results of the simulations are shown in Fig. 5



⁽c) Velocity = 2 m/s

Fig. 5. Settling of solids as a function of solids density for 45 μ m particles at (a) 0.5 m/s, (b) 1 m/s and (c) 2 m/s

The higher density slurries require a higher velocity to keep them suspended and prevent them from settling at the bottom compared to the lower density slurries. The critical velocity for the slurries with density of 3147 kg/m³ was 0.7 m/s compared to the 4 m/s velocity obtained for the heavier slurries with density of 6300 kg/m³.

c. Influence of Solids Volume Fraction

The effect of solids volume fraction on the critical velocity was investigated by running simulations for 45 µm particles with a solids density of 3147 kg/m3. The solids volume fraction values ranged 2.9%, 5.8% and 10% respectively. The critical velocities were calculated for each case and were numerically assessed as the velocity at which the solids were fully suspended in liquid and hence no settling was observed at the bottom of the pipe. For example, for the slurry consisting of 2.9% volume fraction of solids, the solids were observed to settle at 0.5 m/s and at 0.8 m/s. This can be seen as an increase in the solids volume fraction from the initial 2.9% to 4.19% and 3.68% at the respective velocities. As the velocity was further increased to 1 m/s, the solids do no settle. They remain fully dispersed across the pipe length as the solids volume fraction stays the same as the initial volume fraction value. i.e 2.9%. Any increase in the velocity thereafter shows that the solids remain fully suspended. Hence the critical velocity calculated for the case with solids volume fraction of 2.9% is 1 m/s. TABLE II below shows the solids volume fraction values highlighted in red color for the cases simulated and their corresponding measured critical velocities.

Flow Velocity (m/s)	Solids volume fraction 2.9%	Solids volume fraction 5.8%	Solids volume fraction 10%	
0.5	4.19%	7.96%	12.84%	
0.8	3.68%	7.09%	11.70%	
1	2.90%	6.80%	11.36%	
2	2.90%	6.29%	11.21%	
4	2.90%	5.96%	11.01%	
6	2.90%	5.96%	10.31%	

TABLE II. NUMERICAL SIMULATIONS MATRIX

As the solids volume fraction increases, the critical velocity increases, as expected. For instance, the slurry with solids volume fraction of 2.9% the critical velocity obtained is 1 m/s compared to the 4 m/s obtained for solids volume fraction of 5.8% and 6 m/s for the slurry with solids volume fraction of 10%.

CONCLUSION AND FUTURE WORK

In this paper, the implementation of COMSOL Multiphysics 4.3b has been presented simulating settling of solids as a function of flow velocity, particle size, solids density and solids volume fraction. The numerical results compared very well with the experimental results and empirical correlations. The current model assumes that the particle size is static, but, in actual waste transfers the particle size is dynamic due to particle-particle interactions, precipitation, agglomeration, chemical reactions, etc. A change in the chemical environment influences the properties and quantity of solids in the waste stream, which in turn influences the slurry viscosity. The slurry viscosity and the solids properties both influence the flow properties. Chemistry affects flow and flow affects chemistry. Future work will include expanding the mixture model to investigate such chemical-flow interactions.

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